

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	((("5612906" or ("6401052"))).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 14:20
S2	8	("4229647" "4573000" "4776698" "5285144" "5438330").PN. OR ("6401052").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 14:21
S3	16	("20010056333" "20030215030" "2805677" "3364483" "4342517" "4513425" "5187872" "5297063" "5469369" "5781450" "6307365" "6401052" "6433536" "6693423"). PN. OR ("7263453").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 14:22
S4	538	(702/104).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 14:23
S5	935	(702/105,106,107,113).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 14:29
S6	1	("20070174015").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 15:47
S7	187	(gradient with process\$3) and (ellips \$3) and (normaliz\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:18

S8	1	("7039896").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 18:18
S9	3394	((angle phase\$1) and distanc\$3) with (measur\$3 and (compensat\$3 correct \$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:33
S10	128	(fit\$3 with (conic ellips\$3)) and (distance\$1 with (correct\$3 compensat \$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34
S11	34	S9 and S10	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34
S12	2	((("5612906") or ("6401052")).PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 18:34
S13	0	S12 and S11	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34
S14	34	S11 and S9	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34
S15	0	S9 and S12	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34
S16	0	S10 and S12	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:34

S17	10	("5202842" "5463393" "5485407"). PN. OR ("5612906").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 18:35
S18	79	(huynh with phuong) and "2857"	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:17
S19	4	("20040084241" "4753308" "6138788" "6876911").PN. OR ("7239972").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:30
S20	7989	(steer\$3 with angle\$1 with sensor\$1) and (automobile\$1 car\$1 vehicle\$1)	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:55
S21	0	(fit\$3 with (conic ellips\$3)) and (distance\$1 with (correct\$3 compensat \$3)) and (offset\$1 with value\$1) and (least with squar\$3 with error\$1) and (gradient with process\$3)	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:56
S22	0	(linear\$1 with equation\$1) and (distance with measur\$3) and (measur \$3 with offset\$3 with value\$1) and (fitt \$3 with (linear\$3 regress\$3)) and ((compensat\$3 correct\$3 filter\$3) with ((phase\$1 angle\$1) and (amplitud\$3 magnitude\$1)) with error\$1)	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:57
S23	538	(702/104).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 19:58
S24	935	(702/105,106,107,113).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/01/29 19:58

S25	3	S23 and S24 and (distance\$1 with (correct\$3 compensat\$3 measur\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:58
S26	9	("3600674" "4630228" "5062703" "5068614" "5650728" "5949236" "5994905" "6075628" "6614237"). PN. OR ("7171322").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:58
S27	8	("4229647" "4573000" "4776698" "5285144" "5438330").PN. OR ("6401052").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:58
S28	86	(steer\$3 with angle\$1 with sensor\$1) and (automobile\$1 car\$1 vehicle\$1) and S9	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:59
S29	0	S28 and S23	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:59
S30	0	S28 and S24	US-PGPUB; USPAT; USOCR	OR	ON	2008/01/29 19:59
S31	1550	(702/104,105,106,107,113).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2008/08/01 16:11
S32	3598	((angle phase\$1) and distanc\$3) with (measur\$3 and (compensat\$3 correct \$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/08/01 16:11
S33	3598	((angle phase\$1) and distanc\$3) with (measur\$3 and (compensat\$3 correct \$3))	US-PGPUB; USPAT; USOCR	OR	ON	2008/08/01 16:11

S34	90	(steer\$3 with angle\$1 with sensor\$1) and (automobile\$1 car\$1 vehicle\$1) and S33	US-PGPUB; USPAT; USOCR	OR	ON	2008/08/01 16:11
S35	7141	(702/94-97,111-113,188-191,104-107). CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/07/13 17:19
S36	164	(fit\$3 with (conic ellips\$3)) and (distance\$1 with (correct\$3 compensat\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2009/07/13 17:41
S37	0	S35 and S36	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 17:43
S38	3932	((angle phase\$1) and distanc\$3) with (measur\$3 and (compensat\$3 correct\$3))	US-PGPUB; USPAT; USOCR	OR	ON	2009/07/13 17:43
S39	49	S35 and S38	US-PGPUB; USPAT; USOCR	OR	ON	2009/07/13 18:06
S40	87	(sensor\$1 near (system\$1 network\$1 node\$1)) and ((angle phase) with error\$1) and compensat\$3 and (linear with system\$1 with equation\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:07

S41	7	S40 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:08
S42	7	(sensor\$1 near (system\$1 network\$1 node\$1)) and ((angle phase) with error \$1) and compensat\$3 and (linear with system\$1 with equation\$1) and ellips \$3 and (magnetic\$3 with fiel\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:08
S43	1	(sensor\$1 near (system\$1 network\$1 node\$1)) and ((angle phase) with error \$1) and compensat\$3 and (linear with system\$1 with equation\$1) and ellips \$3 and (magnetic\$3 with fiel\$1) and (signal\$1 with measur\$4)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:09
S44	1	S43 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:09
S45	1	((sensor\$1 near (system\$1 network\$1 node\$1)) and ((angle phase) with error \$1) and compensat\$3 and (linear with system\$1 with equation\$1) and ellips \$3 and (magnetic\$3 with fiel\$1) and (signal\$1 with measur\$4)).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:09

S46	13	(sensor\$1 with (system\$1 network\$1 node\$1)) and (linear with equation\$1 with system\$1) and ((fit\$3 with regress \$3) (least with squar\$3)) and (rotat\$3 with magnetic) and (object\$3 with (movement\$1 mov\$3))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:10
S47	1	(sensor\$1 with (system\$1 network\$1 node\$1)) and (linear with equation\$1 with system\$1) and ((fit\$3 with regress \$3) (least with squar\$3)) and (rotat\$3 with magnetic) and (object\$3 with (movement\$1 mov\$3)) and (measur\$3 with signal\$1) and ((sinusoidal cosinusoidal) with signal\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:11
S48	1	S47 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:12
S49	1	(sensor\$1 with (system\$1 network\$1 node\$1)) and (linear with equation\$1 with system\$1) and ((fit\$3 with regress \$3) (least with squar\$3)) and (rotat\$3 with magnetic) and (object\$3 with (movement\$1 mov\$3)) and (measur\$3 with signal\$1) and ((sinusoidal cosinusoidal) with signal\$1) and (least with square with error\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:12

S50	1	S49 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:13
S51	1	(sensor\$1 with (system\$1 network\$1 node\$1)) and (linear with equation\$1 with system\$1) and ((fit\$3 with regress \$3) (least with squar\$3)) and (rotat\$3 with magnetic) and (object\$3 with (movement\$1 mov\$3)) and (measur\$3 with signal\$1) and ((sinusoidal cosinusoidal) with signal\$1) and (least with square with error\$1) and ((angle phase\$1 amplitude magnitude) with error\$1) and compensat\$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:13
S52	1	S51 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:14

S53	1	((sensor\$1 with (system\$1 network\$1 node\$1)) and (linear with equation\$1 with system\$1) and ((fit\$3 with regress \$3) (least with squar\$3)) and (rotat\$3 with magnetic) and (object\$3 with (movement\$1 mov\$3)) and (measur\$3 with signal\$1) and ((sinusoidal cosinusoidal) with signal\$1) and (least with square with error\$1) and ((angle phase\$1 amplitude magnitude) with error\$1) and compensat\$3).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:14
S54	150	(magnetic with field) and (object\$1 with mov\$3) and (compensat\$3 with (angle \$1 phase) with error\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:14
S55	1	(magnetic with field) and (object\$1 with mov\$3) and (compensat\$3 with (angle \$1 phase) with error\$1) and ((sinusoidal cosinusoidal) with signal \$1) and (correct with parameter\$1) and (linear with equation with system\$1)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:15
S56	2	S54 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:15

S57	1	(magnetic with field) and (object\$1 with mov\$3) and (compensat\$3 with (angle \$1 phase) with error\$1) and ((sinusoidal cosinusoidal) with signal \$1) and (correct with parameter\$1) and (linear with equation with system\$1) and (sensor\$1 with (system\$1 network \$1 node\$1))	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:16
S58	1	S57 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:16
S59	0	((magnetic with field) and (object\$1 with mov\$3) and (compensat\$3 with (angle\$1 phase) with error\$1) and ((sinusoidal cosinusoidal) with signal \$1) and (correct with parameter\$1) and (linear with equation with system\$1) and (sensor\$1 with (system\$1 network \$1 node\$1))).clm.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/07/13 18:16

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